

# Induction of spectral gaps for the cohomological Laplacians of $SL_n(\mathbb{Z})$ and $SAut(F_n)$

Piotr Mizerka

*joint work with Marek Kaluba (KIT)*

Institute of Mathematics, Polish Academy of Sciences

Spanish+Polish Mathematical Meeting  
Łódź, 07.09.2023

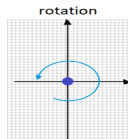
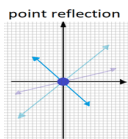
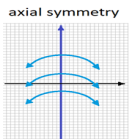
# Outline

- 1 Motivation
- 2 Induction – idea
- 3 Induction for  $\Delta_1$
- 4 Final remarks

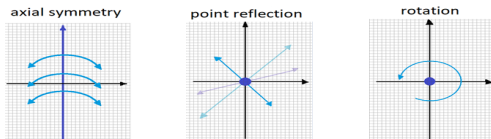
# Motivation

# Group cohomology and property (T)

# Group cohomology and property (T)

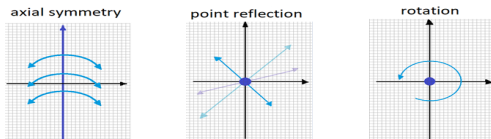


# Group cohomology and property (T)



- Generalization: symmetries must have fixed points

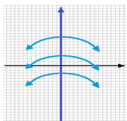
# Group cohomology and property (T)



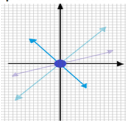
- Generalization: symmetries must have fixed points

# Group cohomology and property (T)

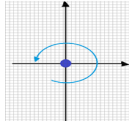
axial symmetry



point reflection



rotation



- Generalization: symmetries must have fixed points

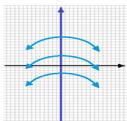
## Definition

$G$  has *Kazhdan's property (T)* if every continuous isometric affine action of  $G$  on a real Hilbert space has a fixed point.

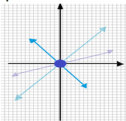


# Group cohomology and property (T)

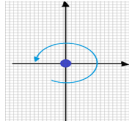
axial symmetry



point reflection



rotation

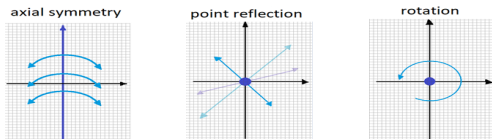


- Generalization: symmetries must have fixed points

## Definition

$G$  has *Kazhdan's property (T)* if every continuous isometric affine action of  $G$  on a real Hilbert space has a fixed point.

# Group cohomology and property (T)



- Generalization: symmetries must have fixed points

## Definition

$G$  has *Kazhdan's property (T)* if every continuous isometric affine action of  $G$  on a real Hilbert space has a fixed point.

## Theorem (Shalom et. al.)

$G$  has *Kazhdan's property (T)* if  $H^1(G, \pi) = 0$  for every orthogonal representation  $\pi : G \rightarrow \mathcal{B}(\mathcal{H})$ .

# Applications – expanders

# Applications – expanders

- Expanders – sparse graphs with good connectivity properties

# Applications – expanders

- Expanders – sparse graphs with good connectivity properties
- $G = (V, E)$

# Applications – expanders

- Expanders – sparse graphs with good connectivity properties
- $G = (V, E)$
- Cheeger constant:  $h(G) = \inf_{1 \leq \#A \leq \#V/2} \frac{\#E(A, V \setminus A)}{\#A}$

# Applications – expanders

- Expanders – sparse graphs with good connectivity properties
- $G = (V, E)$
- Cheeger constant:  $h(G) = \inf_{1 \leq \#A \leq \#V/2} \frac{\#E(A, V \setminus A)}{\#A}$
- Expander family:  $|G_n| \rightarrow \infty$  s.t.  $\liminf_{n \rightarrow \infty} \frac{h(G_n)}{\deg(G_n)} > 0$

# Applications – expanders

- Expanders – sparse graphs with good connectivity properties
- $G = (V, E)$
- Cheeger constant:  $h(G) = \inf_{1 \leq \#A \leq \#V/2} \frac{\#E(A, V \setminus A)}{\#A}$
- Expander family:  $|G_n| \rightarrow \infty$  s.t.  $\liminf_{n \rightarrow \infty} \frac{h(G_n)}{\deg(G_n)} > 0$
- (T) yields expanders:  $G_n := G/N_n$ ,  $G$  has (T) (Margulis '80s)



# Applications – Product Replacement Algorithm

# Applications – Product Replacement Algorithm

- Product Replacement Algorithm – generating random elements in groups (Leedham-Green and Soicher, 1995)

# Applications – Product Replacement Algorithm

- Product Replacement Algorithm – generating random elements in groups (Leedham-Green and Soicher, 1995)
- one observed good performance of PRA in practice ...

# Applications – Product Replacement Algorithm

- Product Replacement Algorithm – generating random elements in groups (Leedham-Green and Soicher, 1995)
- one observed good performance of PRA in practice ...
- ... good performance of PRA would follow from property (T) of  $\text{Aut}(F_n)$  (Lubotzky and Pak, 2000)

# Applications – Product Replacement Algorithm

- Product Replacement Algorithm – generating random elements in groups (Leedham-Green and Soicher, 1995)
- one observed good performance of PRA in practice ...
- ... good performance of PRA would follow from property (T) of  $\text{Aut}(F_n)$  (Lubotzky and Pak, 2000)

# Applications – Product Replacement Algorithm

- Product Replacement Algorithm – generating random elements in groups (Leedham-Green and Soicher, 1995)
- one observed good performance of PRA in practice ...
- ... good performance of PRA would follow from property (T) of  $\text{Aut}(F_n)$  (Lubotzky and Pak, 2000)

**Theorem (Kaluba, Kielak, Nowak, Ozawa, 2019, 2021)**

*$\text{Aut}(F_n)$  has property (T) if  $n \geq 5$ .*

# Group ring conditions and an application to $SL_n(\mathbb{Z})$

# Group ring conditions and an application to $SL_n(\mathbb{Z})$



# Group ring conditions and an application to $SL_n(\mathbb{Z})$

## Theorem (Ozawa, 2016)

*$G$  has property (T) iff there exists  $\lambda > 0$  such that  $\Delta^2 - \lambda\Delta \geq 0$ .*

# Group ring conditions and an application to $SL_n(\mathbb{Z})$

## Theorem (Ozawa, 2016)

*$G$  has property (T) iff there exists  $\lambda > 0$  such that  $\Delta^2 - \lambda\Delta \geq 0$ .*

# Group ring conditions and an application to $SL_n(\mathbb{Z})$

## Theorem (Ozawa, 2016)

*$G$  has property (T) iff there exists  $\lambda > 0$  such that  $\Delta^2 - \lambda\Delta \geq 0$ .*

## Theorem (Bader, Nowak, Sauer, 2020, 2023)

*$G$  has property (T) iff there exists  $\lambda > 0$  such that  $\Delta_1 - \lambda I \geq 0$ .*

# Group ring conditions and an application to $SL_n(\mathbb{Z})$

## Theorem (Ozawa, 2016)

*$G$  has property (T) iff there exists  $\lambda > 0$  such that  $\Delta^2 - \lambda\Delta \geq 0$ .*

## Theorem (Bader, Nowak, Sauer, 2020, 2023)

*$G$  has property (T) iff there exists  $\lambda > 0$  such that  $\Delta_1 - \lambda I \geq 0$ .*

# Group ring conditions and an application to $SL_n(\mathbb{Z})$

## Theorem (Ozawa, 2016)

*$G$  has property (T) iff there exists  $\lambda > 0$  such that  $\Delta^2 - \lambda\Delta \geq 0$ .*

## Theorem (Bader, Nowak, Sauer, 2020, 2023)

*$G$  has property (T) iff there exists  $\lambda > 0$  such that  $\Delta_1 - \lambda I \geq 0$ .*

## Theorem (Kaluba, M., 2023)

*For  $SL_n(\mathbb{Z})$ , one has  $\Delta_1 - 0.217(n - 2)I \geq 0$ .*

# Group ring conditions – definitions

# Group ring conditions – definitions

- the group ring:  $\mathbb{R}G = \{\sum_{g \in G} \lambda_g g \mid \lambda_g \in \mathbb{R}\}$

# Group ring conditions – definitions

- the group ring:  $\mathbb{R}G = \{\sum_{g \in G} \lambda_g g \mid \lambda_g \in \mathbb{R}\}$
- \*-involution in  $\mathbb{R}G$ :  $\xi^* = \sum_{g \in G} \xi_g g^{-1}$



## Group ring conditions – definitions

- the group ring:  $\mathbb{R}G = \{\sum_{g \in G} \lambda_g g \mid \lambda_g \in \mathbb{R}\}$
- \*-involution in  $\mathbb{R}G$ :  $\xi^* = \sum_{g \in G} \xi_g g^{-1}$
- \*-involution in  $M_{m \times n}(\mathbb{R}G)$ :  $(M^*)_{i,j} = (M_{j,i})^*$

## Group ring conditions – definitions

- the group ring:  $\mathbb{R}G = \{\sum_{g \in G} \lambda_g g \mid \lambda_g \in \mathbb{R}\}$
- \*-involution in  $\mathbb{R}G$ :  $\xi^* = \sum_{g \in G} \xi_g g^{-1}$
- \*-involution in  $\mathbb{M}_{m \times n}(\mathbb{R}G)$ :  $(M^*)_{i,j} = (M_{j,i})^*$
- $M \geq 0$  iff there exist  $M_1, \dots, M_l \in \mathbb{M}_{n \times n}(\mathbb{R}G)$  such that

$$M = M_1^* M_1 + \dots + M_l^* M_l.$$

# Group ring conditions – definitions

- the group ring:  $\mathbb{R}G = \{\sum_{g \in G} \lambda_g g \mid \lambda_g \in \mathbb{R}\}$
- \*-involution in  $\mathbb{R}G$ :  $\xi^* = \sum_{g \in G} \xi_g g^{-1}$
- \*-involution in  $\mathbb{M}_{m \times n}(\mathbb{R}G)$ :  $(M^*)_{i,j} = (M_{j,i})^*$
- $M \geq 0$  iff there exist  $M_1, \dots, M_l \in \mathbb{M}_{n \times n}(\mathbb{R}G)$  such that

$$M = M_1^* M_1 + \dots + M_l^* M_l.$$

- $\Delta \in \mathbb{R}G$ ,  $\Delta_1 \in \mathbb{M}_{|S| \times |S|}(\mathbb{R}G)$

# Induction – idea

# Laplacian definitions

# Laplacian definitions

- $G = \langle s_1, \dots, s_n \mid r_1, \dots, r_m \rangle$

# Laplacian definitions

- $G = \langle s_1, \dots, s_n \mid r_1, \dots, r_m \rangle$

- $d_0 = \begin{bmatrix} 1 - s_1 \\ \vdots \\ 1 - s_n \end{bmatrix}$

# Laplacian definitions

- $G = \langle s_1, \dots, s_n | r_1, \dots, r_m \rangle$

- $d_0 = \begin{bmatrix} 1 - s_1 \\ \vdots \\ 1 - s_n \end{bmatrix}$

- Jacobian:  $d_1 = \begin{bmatrix} \partial r_i \\ \partial s_j \end{bmatrix}$



# Laplacian definitions

- $G = \langle s_1, \dots, s_n | r_1, \dots, r_m \rangle$

- $d_0 = \begin{bmatrix} 1 - s_1 \\ \vdots \\ 1 - s_n \end{bmatrix}$

- Jacobian:  $d_1 = \begin{bmatrix} \partial r_i \\ \partial s_j \end{bmatrix}$

- $\Delta = d_0^* d_0 = \sum_{i=1}^n (1 - s_i)^* (1 - s_i)$

# Laplacian definitions

- $G = \langle s_1, \dots, s_n | r_1, \dots, r_m \rangle$

- $d_0 = \begin{bmatrix} 1 - s_1 \\ \vdots \\ 1 - s_n \end{bmatrix}$

- Jacobian:  $d_1 = \begin{bmatrix} \partial r_i \\ \partial s_j \end{bmatrix}$

- $\Delta = d_0^* d_0 = \sum_{i=1}^n (1 - s_i)^* (1 - s_i)$

- $\Delta_1 = d_1^* d_1 + d_0 d_0^*$

# Fox derivatives

# Fox derivatives

- $G = \langle s_1, \dots, s_n \mid r_1, \dots, r_m \rangle$

# Fox derivatives

- $G = \langle s_1, \dots, s_n \mid r_1, \dots, r_m \rangle$

# Fox derivatives

- $G = \langle s_1, \dots, s_n \mid r_1, \dots, r_m \rangle$

## Definition (Fox, '50s)

The differentials  $\frac{\partial}{\partial s_j} : \mathbb{R}F_n \rightarrow \mathbb{R}G$ ,  $F_n = \langle s_1, \dots, s_n \rangle$  are defined by:

# Fox derivatives

- $G = \langle s_1, \dots, s_n \mid r_1, \dots, r_m \rangle$

## Definition (Fox, '50s)

The differentials  $\frac{\partial}{\partial s_j} : \mathbb{R}F_n \rightarrow \mathbb{R}G$ ,  $F_n = \langle s_1, \dots, s_n \rangle$  are defined by:

- $\frac{\partial s_i}{\partial s_j} = \delta_{i,j}$ ,  $\frac{\partial s_j^{-1}}{\partial s_j} = -s_j^{-1}$ , and  $\frac{\partial s_i^{\pm 1}}{\partial s_j} = 0$  for  $i \neq j$

# Fox derivatives

- $G = \langle s_1, \dots, s_n \mid r_1, \dots, r_m \rangle$

## Definition (Fox, '50s)

The differentials  $\frac{\partial}{\partial s_j} : \mathbb{R}F_n \rightarrow \mathbb{R}G$ ,  $F_n = \langle s_1, \dots, s_n \rangle$  are defined by:

- $\frac{\partial s_i}{\partial s_j} = \delta_{i,j}$ ,  $\frac{\partial s_j^{-1}}{\partial s_j} = -s_j^{-1}$ , and  $\frac{\partial s_i^{\pm 1}}{\partial s_j} = 0$  for  $i \neq j$
- product rule:  $\frac{\partial(uv)}{\partial s_j} = \frac{\partial u}{\partial s_j} + u \frac{\partial v}{\partial s_j}$ .



# Fox derivatives

- $G = \langle s_1, \dots, s_n \mid r_1, \dots, r_m \rangle$

## Definition (Fox, '50s)

The differentials  $\frac{\partial}{\partial s_j} : \mathbb{R}F_n \rightarrow \mathbb{R}G$ ,  $F_n = \langle s_1, \dots, s_n \rangle$  are defined by:

- $\frac{\partial s_i}{\partial s_j} = \delta_{i,j}$ ,  $\frac{\partial s_j^{-1}}{\partial s_j} = -s_j^{-1}$ , and  $\frac{\partial s_i^{\pm 1}}{\partial s_j} = 0$  for  $i \neq j$
- product rule:  $\frac{\partial(uv)}{\partial s_j} = \frac{\partial u}{\partial s_j} + u \frac{\partial v}{\partial s_j}$ .

# Fox derivatives

- $G = \langle s_1, \dots, s_n \mid r_1, \dots, r_m \rangle$

## Definition (Fox, '50s)

The differentials  $\frac{\partial}{\partial s_j} : \mathbb{R}F_n \rightarrow \mathbb{R}G$ ,  $F_n = \langle s_1, \dots, s_n \rangle$  are defined by:

- $\frac{\partial s_i}{\partial s_j} = \delta_{i,j}$ ,  $\frac{\partial s_j^{-1}}{\partial s_j} = -s_j^{-1}$ , and  $\frac{\partial s_i^{\pm 1}}{\partial s_j} = 0$  for  $i \neq j$
- product rule:  $\frac{\partial(uv)}{\partial s_j} = \frac{\partial u}{\partial s_j} + u \frac{\partial v}{\partial s_j}$ .

## Definition (Fox, '50s)

The Fox derivatives are the elements  $\frac{\partial r_i}{\partial s_j} \in \mathbb{R}G$ .

# Presentations of $SL_n(\mathbb{Z})$ and $SAut(F_n)$

# Presentations of $SL_n(\mathbb{Z})$ and $SAut(F_n)$

- $SL_n(\mathbb{Z}) = \langle E_{ij} | [E_{ij}, E_{kl}], [E_{ij}, E_{jk}]E_{ik}^{-1}, \dots \rangle$

# Presentations of $SL_n(\mathbb{Z})$ and $SAut(F_n)$

- $SL_n(\mathbb{Z}) = \langle E_{ij} | [E_{ij}, E_{kl}], [E_{ij}, E_{jk}]E_{ik}^{-1}, \dots \rangle$
- $SAut(F_n) = \langle \lambda_{ij}, \rho_{ij} | \mathcal{R}, \dots \rangle$

# Presentations of $SL_n(\mathbb{Z})$ and $SAut(F_n)$

- $SL_n(\mathbb{Z}) = \langle E_{ij} | [E_{ij}, E_{kl}], [E_{ij}, E_{jk}]E_{ik}^{-1}, \dots \rangle$
- $SAut(F_n) = \langle \lambda_{ij}, \rho_{ij} | \mathcal{R}, \dots \rangle$

$$\begin{aligned} \mathcal{R} : & [\lambda_{i,j}, \rho_{ij}], \quad [\lambda_{ij}, \lambda_{kl}], \quad [\rho_{ij}, \rho_{kl}], \quad [\lambda_{ij}, \rho_{kl}], \\ & [\lambda_{ij}, \lambda_{kj}], \quad [\rho_{ij}, \rho_{kj}], \quad [\lambda_{ij}, \rho_{ik}], \quad [\lambda_{i,j}, \rho_{kj}], \\ & \lambda_{ik}^{\pm}[\lambda_{jk}^{\pm}, \lambda_{ij}^{-1}], \quad \rho_{ik}^{\pm}[\rho_{jk}^{\pm}, \rho_{ij}^{-1}], \quad \lambda_{ik}^{\pm}[\rho_{jk}^{\mp}, \lambda_{ij}], \quad \rho_{ik}^{\pm}[\lambda_{jk}^{\mp}, \rho_{ij}] \end{aligned}$$

# Presentations of $SL_n(\mathbb{Z})$ and $SAut(F_n)$

- $SL_n(\mathbb{Z}) = \langle E_{ij} | [E_{ij}, E_{kl}], [E_{ij}, E_{jk}]E_{ik}^{-1}, \dots \rangle$
- $SAut(F_n) = \langle \lambda_{ij}, \rho_{ij} | \mathcal{R}, \dots \rangle$

$$\begin{aligned} \mathcal{R} : & [\lambda_{i,j}, \rho_{ij}], \quad [\lambda_{ij}, \lambda_{kl}], \quad [\rho_{ij}, \rho_{kl}], \quad [\lambda_{ij}, \rho_{kl}], \\ & [\lambda_{ij}, \lambda_{kj}], \quad [\rho_{ij}, \rho_{kj}], \quad [\lambda_{ij}, \rho_{ik}], \quad [\lambda_{i,j}, \rho_{kj}], \\ & \lambda_{ik}^{\pm}[\lambda_{jk}^{\pm}, \lambda_{ij}^{-1}], \quad \rho_{ik}^{\pm}[\rho_{jk}^{\pm}, \rho_{ij}^{-1}], \quad \lambda_{ik}^{\pm}[\rho_{jk}^{\mp}, \lambda_{ij}], \quad \rho_{ik}^{\pm}[\lambda_{jk}^{\mp}, \rho_{ij}] \end{aligned}$$

$$\lambda_{ij}(s_k) = \begin{cases} s_j s_i & \text{if } k = i, \\ s_k & \text{otherwise,} \end{cases} \quad \rho_{ij}(s_k) = \begin{cases} s_i s_j & \text{if } k = i, \\ s_k & \text{otherwise.} \end{cases}$$

# Decomposition of $\Delta^2$



# Decomposition of $\Delta^2$

- Kaluba, Kielak, Nowak, 2021:  $\Delta^2 = \text{Sq} + \text{Adj} + \text{Op}$

# Decomposition of $\Delta^2$

- Kaluba, Kielak, Nowak, 2021:  $\Delta^2 = \text{Sq} + \text{Adj} + \text{Op}$
- $E_n$  – edges of the standard  $n$ -simplex

# Decomposition of $\Delta^2$

- Kaluba, Kielak, Nowak, 2021:  $\Delta^2 = \text{Sq} + \text{Adj} + \text{Op}$
- $E_n$  – edges of the standard  $n$ -simplex
- $\text{Sq} = \sum_{e \in E_n} \Delta_e^2$

# Decomposition of $\Delta^2$

- Kaluba, Kielak, Nowak, 2021:  $\Delta^2 = \text{Sq} + \text{Adj} + \text{Op}$
- $E_n$  – edges of the standard  $n$ -simplex
- $\text{Sq} = \sum_{e \in E_n} \Delta_e^2$
- $\text{Adj} = \sum_{e \in E_n} \left( \Delta_e \sum_{f \in \text{Adj}(e)} \Delta_f \right)$

# Decomposition of $\Delta^2$

- Kaluba, Kielak, Nowak, 2021:  $\Delta^2 = \text{Sq} + \text{Adj} + \text{Op}$
- $E_n$  – edges of the standard  $n$ -simplex
- $\text{Sq} = \sum_{e \in E_n} \Delta_e^2$
- $\text{Adj} = \sum_{e \in E_n} \left( \Delta_e \sum_{f \in \text{Adj}(e)} \Delta_f \right)$
- $\text{Op} = \sum_{e \in E_n} \left( \Delta_e \sum_{f \in \text{Op}(e)} \Delta_f \right)$

# Decomposition of $\Delta_1$

# Decomposition of $\Delta_1$

- $\Delta_1 = \Delta_1^+ + \Delta_1^-$ ,  $\Delta_1^+ = d_1^* d_1$ ,  $\Delta_1^- = d_0 d_0^*$

# Decomposition of $\Delta_1$

- $\Delta_1 = \Delta_1^+ + \Delta_1^-$ ,  $\Delta_1^+ = d_1^* d_1$ ,  $\Delta_1^- = d_0 d_0^*$
- $\Delta_1^- = \text{Sq}^- + \text{Adj}^- + \text{Op}^-$



# Decomposition of $\Delta_1$

- $\Delta_1 = \Delta_1^+ + \Delta_1^-$ ,  $\Delta_1^+ = d_1^* d_1$ ,  $\Delta_1^- = d_0 d_0^*$
- $\Delta_1^- = \text{Sq}^- + \text{Adj}^- + \text{Op}^-$
- $\Delta_1^+ = \text{Sq}^+ + \text{Adj}^+ + \text{Op}^+$

# Decomposition of $\Delta_1$

- $\Delta_1 = \Delta_1^+ + \Delta_1^-$ ,  $\Delta_1^+ = d_1^* d_1$ ,  $\Delta_1^- = d_0 d_0^*$
- $\Delta_1^- = \text{Sq}^- + \text{Adj}^- + \text{Op}^-$
- $\Delta_1^+ = \text{Sq}^+ + \text{Adj}^+ + \text{Op}^+$

$$(\text{Sq}^+)_{s,t} = \sum_{r \in \text{Sq}_{\mathcal{R}}} \left( \frac{\partial r}{\partial s} \right)^* \frac{\partial r}{\partial t}, \quad (\text{Adj}^+)_{s,t} = \sum_{r \in \text{Adj}_{\mathcal{R}}} \left( \frac{\partial r}{\partial s} \right)^* \frac{\partial r}{\partial t},$$
$$(\text{Op}^+)_{s,t} = \sum_{r \in \text{Op}_{\mathcal{R}}} \left( \frac{\partial r}{\partial s} \right)^* \frac{\partial r}{\partial t}.$$

# Induction strategy

# Induction strategy

- Observation:  $\mathcal{R} \subseteq \mathcal{R}'$ ,  $(\Delta_1)_{\mathcal{R}} - \lambda I \geq 0 \Rightarrow (\Delta_1)_{\mathcal{R}'} - \lambda I \geq 0$

$\Delta^2$ (Kaluba, Kielak, Nowak):       $\Delta_1$ :

# Induction strategy

- Observation:  $\mathcal{R} \subseteq \mathcal{R}'$ ,  $(\Delta_1)_{\mathcal{R}} - \lambda I \geq 0 \Rightarrow (\Delta_1)_{\mathcal{R}'} - \lambda I \geq 0$

$\Delta^2$ (Kaluba, Kielak, Nowak):       $\Delta_1$ :

# Induction strategy

- Observation:  $\mathcal{R} \subseteq \mathcal{R}'$ ,  $(\Delta_1)_{\mathcal{R}} - \lambda I \geq 0 \Rightarrow (\Delta_1)_{\mathcal{R}'} - \lambda I \geq 0$

$\Delta^2$ (Kaluba, Kielak, Nowak):  $\Delta_1$ :

- $Sq, Op \geq 0$

# Induction strategy

- Observation:  $\mathcal{R} \subseteq \mathcal{R}'$ ,  $(\Delta_1)_{\mathcal{R}} - \lambda I \geq 0 \Rightarrow (\Delta_1)_{\mathcal{R}'} - \lambda I \geq 0$

$\Delta^2$  (Kaluba, Kielak, Nowak):  $\Delta_1$ :

- $Sq, Op \geq 0$
- $Adj_m + k Op_m - \lambda \Delta_m \geq 0 \Rightarrow \Delta_n^2 - \lambda' \Delta_n \geq 0$  for  $n \gg m$

# Induction strategy

- Observation:  $\mathcal{R} \subseteq \mathcal{R}'$ ,  $(\Delta_1)_{\mathcal{R}} - \lambda I \geq 0 \Rightarrow (\Delta_1)_{\mathcal{R}'} - \lambda I \geq 0$

$\Delta^2$  (Kaluba, Kielak, Nowak):

- $Sq, Op \geq 0$
- $Adj_m + k Op_m - \lambda \Delta_m \geq 0 \Rightarrow \Delta_n^2 - \lambda' \Delta_n \geq 0$  for  $n \gg m$

$\Delta_1$ :

- $Sq^\pm, Op^+ + 2Op^- \geq 0$



# Induction strategy

- Observation:  $\mathcal{R} \subseteq \mathcal{R}'$ ,  $(\Delta_1)_{\mathcal{R}} - \lambda I \geq 0 \Rightarrow (\Delta_1)_{\mathcal{R}'} - \lambda I \geq 0$

$\Delta^2$  (Kaluba, Kielak, Nowak):

- $Sq, Op \geq 0$
- $Adj_m + k Op_m - \lambda \Delta_m \geq 0 \Rightarrow \Delta_n^2 - \lambda' \Delta_n \geq 0$  for  $n \gg m$

$\Delta_1$ :

- $Sq^\pm, Op^+ + 2Op^- \geq 0$
- $Adj_m - \lambda I \geq 0 \Rightarrow Adj_n - \lambda' I \geq 0$  for  $n \geq m$

# Induction for $\Delta_1$

# Positivity of square and opposite parts

# Positivity of square and opposite parts

# Positivity of square and opposite parts

## Lemma

*The matrices  $Sq_n^-$  and  $Op_n^+ + 2Op_n^-$  are positive.*

# Positivity of square and opposite parts

## Lemma

*The matrices  $Sq_n^-$  and  $Op_n^+ + 2Op_n^-$  are positive.*

## Proof.



# Positivity of square and opposite parts

## Lemma

*The matrices  $Sq_n^-$  and  $Op_n^+ + 2Op_n^-$  are positive.*

## Proof.

- $Sq_n^- = \sum_{1 \leq i \neq j \leq n} d^{i,j} (d^{i,j})^*$ ,  $d^{i,j}$  – column vector with  $1 - s$  for  $s$  on indices  $\bar{i}$  and  $\bar{j}$



# Positivity of square and opposite parts

## Lemma

*The matrices  $Sq_n^-$  and  $Op_n^+ + 2Op_n^-$  are positive.*

## Proof.

- $Sq_n^- = \sum_{1 \leq i \neq j \leq n} d^{i,j} (d^{i,j})^*$ ,  $d^{i,j}$  – column vector with  $1 - s$  for  $s$  on indices  $\bar{i}$  and  $\bar{j}$
- diagonal part of  $Op^-$  vanishes, and for  $Op^+$  is positive





# Positivity of square and opposite parts

## Lemma

The matrices  $Sq_n^-$  and  $Op_n^+ + 2Op_n^-$  are positive.

## Proof.

- $Sq_n^- = \sum_{1 \leq i \neq j \leq n} d^{i,j} (d^{i,j})^*$ ,  $d^{i,j}$  – column vector with  $1 - s$  for  $s$  on indices  $i$  and  $j$
- diagonal part of  $Op^-$  vanishes, and for  $Op^+$  is positive
- the rest cancels out:

$$\begin{aligned} (Op_n^+)_{\alpha_{ij}, \beta_{kl}} &= \left( \frac{\partial[\alpha_{ij}, \beta_{kl}]}{\partial \alpha_{ij}} \right)^* \frac{\partial[\alpha_{ij}, \beta_{kl}]}{\partial \beta_{kl}} + \left( \frac{\partial[\beta_{kl}, \alpha_{ij}]}{\partial \alpha_{ij}} \right)^* \frac{\partial[\beta_{kl}, \alpha_{ij}]}{\partial \beta_{kl}} \\ &= -2(1 - \alpha_{ij})(1 - \beta_{kl})^*. \end{aligned}$$



# Symmetrization

# Symmetrization

- $G_n = \mathrm{SL}_n(\mathbb{Z}), \mathrm{SAut}(F_n)$

# Symmetrization

- $G_n = \mathrm{SL}_n(\mathbb{Z}), \mathrm{SAut}(F_n)$
- the symmetric group  $\Sigma_n$  acts on  $G_n$ :  $\omega_{i,j} \mapsto \omega_{\sigma(i),\sigma(j)}$

# Symmetrization

- $G_n = \mathrm{SL}_n(\mathbb{Z}), \mathrm{SAut}(F_n)$
- the symmetric group  $\Sigma_n$  acts on  $G_n$ :  $\omega_{i,j} \mapsto \omega_{\sigma(i),\sigma(j)}$
- this induces the action on  $\mathbb{M}_{|\mathcal{S}_n| \times |\mathcal{S}_n|}(\mathbb{R}G_n)$ :  
 $(\sigma A)_{s,t} = \sigma(A_{\sigma^{-1}s, \sigma^{-1}t})$

# Symmetrization

- $G_n = \mathrm{SL}_n(\mathbb{Z}), \mathrm{SAut}(F_n)$
- the symmetric group  $\Sigma_n$  acts on  $G_n$ :  $\omega_{i,j} \mapsto \omega_{\sigma(i),\sigma(j)}$
- this induces the action on  $\mathbb{M}_{|\mathcal{S}_n| \times |\mathcal{S}_n|}(\mathbb{R}G_n)$ :  
 $(\sigma A)_{s,t} = \sigma(A_{\sigma^{-1}s,\sigma^{-1}t})$
- observation:  $\sigma A \geq 0$ , provided  $A \geq 0$

# Symmetrization

- $G_n = \text{SL}_n(\mathbb{Z}), \text{SAut}(F_n)$
- the symmetric group  $\Sigma_n$  acts on  $G_n$ :  $\omega_{i,j} \mapsto \omega_{\sigma(i),\sigma(j)}$
- this induces the action on  $\mathbb{M}_{|\mathcal{S}_n| \times |\mathcal{S}_n|}(\mathbb{R}G_n)$ :  
 $(\sigma A)_{s,t} = \sigma(A_{\sigma^{-1}s, \sigma^{-1}t})$
- observation:  $\sigma A \geq 0$ , provided  $A \geq 0$
- $\text{Adj}_n \approx \sum_{\sigma \in \Sigma_n} \sigma \widetilde{\text{Adj}}_m$  for  $n \geq m$ , provided  $\text{Adj}_m$  is  $\Sigma_m$ -invariant

# Invariance of Adj



# Invariance of Adj

- recall:  $\text{Adj} = \text{Adj}^- + \text{Adj}^+$

# Invariance of Adj

- recall:  $\text{Adj} = \text{Adj}^- + \text{Adj}^+$
- invariance for  $\text{Adj}^-$ :

$$\begin{aligned}(\sigma \text{Adj}^-)_{s,t} &= \sigma \left( \text{Adj}_{\sigma^{-1}s, \sigma^{-1}t}^- \right) = \sigma \left( (1 - \sigma^{-1}s) (1 - \sigma^{-1}t)^* \right) \\ &= (1 - s)(1 - t)^* = \text{Adj}_{s,t}^-.\end{aligned}$$

# Invariance of Adj

- recall:  $\text{Adj} = \text{Adj}^- + \text{Adj}^+$
- invariance for  $\text{Adj}^-$ :

$$\begin{aligned}(\sigma \text{Adj}^-)_{s,t} &= \sigma \left( \text{Adj}^-_{\sigma^{-1}s, \sigma^{-1}t} \right) = \sigma \left( (1 - \sigma^{-1}s) (1 - \sigma^{-1}t)^* \right) \\ &= (1 - s)(1 - t)^* = \text{Adj}^-_{s,t}.\end{aligned}$$

- invariance for  $\text{Adj}^+$  follows from the equivariance of the Jacobian  $d_1$

# Equivariance of the Jacobian

# Equivariance of the Jacobian

- $G = \langle s_1, \dots, s_K \mid r_1, \dots, r_L \rangle$

# Equivariance of the Jacobian

- $G = \langle s_1, \dots, s_K \mid r_1, \dots, r_L \rangle$
- observation: the action of  $\Sigma_m$  on  $G_m$  lifts to the action on the relators, yielding the actions of  $\Sigma_m$  on  $(\mathbb{R}G_m)^K$  and  $(\mathbb{R}G_m)^L$ :

$$\sigma(\xi_1, \dots, \xi_K) = (\sigma^{\xi_{\sigma^{-1}(1)}}, \dots, \sigma^{\xi_{\sigma^{-1}(K)}}),$$

$$\sigma(\xi_1, \dots, \xi_L) = (\sigma^{\xi_{\sigma^{-1}(1)}}, \dots, \sigma^{\xi_{\sigma^{-1}(L)}}).$$

# Equivariance of the Jacobian

- $G = \langle s_1, \dots, s_K \mid r_1, \dots, r_L \rangle$
- observation: the action of  $\Sigma_m$  on  $G_m$  lifts to the action on the relators, yielding the actions of  $\Sigma_m$  on  $(\mathbb{R}G_m)^K$  and  $(\mathbb{R}G_m)^L$ :

$$\sigma(\xi_1, \dots, \xi_K) = (\sigma^{\xi_{\sigma^{-1}(1)}}, \dots, \sigma^{\xi_{\sigma^{-1}(K)}}),$$

$$\sigma(\xi_1, \dots, \xi_L) = (\sigma^{\xi_{\sigma^{-1}(1)}}, \dots, \sigma^{\xi_{\sigma^{-1}(L)}}).$$

- recall:  $d_1 = \left[ \frac{\partial r}{\partial s} \right] : (\mathbb{R}G_m)^K \rightarrow (\mathbb{R}G_m)^L$

# Equivariance of the Jacobian

- $G = \langle s_1, \dots, s_K \mid r_1, \dots, r_L \rangle$
- observation: the action of  $\Sigma_m$  on  $G_m$  lifts to the action on the relators, yielding the actions of  $\Sigma_m$  on  $(\mathbb{R}G_m)^K$  and  $(\mathbb{R}G_m)^L$ :

$$\sigma(\xi_1, \dots, \xi_K) = (\sigma^{\xi_{\sigma^{-1}(1)}}, \dots, \sigma^{\xi_{\sigma^{-1}(K)}}),$$

$$\sigma(\xi_1, \dots, \xi_L) = (\sigma^{\xi_{\sigma^{-1}(1)}}, \dots, \sigma^{\xi_{\sigma^{-1}(L)}}).$$

- recall:  $d_1 = \left[ \frac{\partial r}{\partial s} \right] : (\mathbb{R}G_m)^K \rightarrow (\mathbb{R}G_m)^L$
- the equivariance of  $d_1$  follows from the following relationship:



# Equivariance of the Jacobian

- $G = \langle s_1, \dots, s_K | r_1, \dots, r_L \rangle$
- observation: the action of  $\Sigma_m$  on  $G_m$  lifts to the action on the relators, yielding the actions of  $\Sigma_m$  on  $(\mathbb{R}G_m)^K$  and  $(\mathbb{R}G_m)^L$ :

$$\sigma(\xi_1, \dots, \xi_K) = (\sigma\xi_{\sigma^{-1}(1)}, \dots, \sigma\xi_{\sigma^{-1}(K)}),$$

$$\sigma(\xi_1, \dots, \xi_L) = (\sigma\xi_{\sigma^{-1}(1)}, \dots, \sigma\xi_{\sigma^{-1}(L)}).$$

- recall:  $d_1 = \left[ \frac{\partial r}{\partial s} \right] : (\mathbb{R}G_m)^K \rightarrow (\mathbb{R}G_m)^L$
- the equivariance of  $d_1$  follows from the following relationship:

## Lemma

For any  $\sigma \in \Sigma_m$ ,  $r$ , and  $s$ , we have  $\frac{\partial r}{\partial(\sigma s)} = \sigma \left( \frac{\partial(\sigma^{-1}r)}{\partial s} \right)$ .

# Spectral gaps for $SL_n(\mathbb{Z})$

# Spectral gaps for $SL_n(\mathbb{Z})$

# Spectral gaps for $SL_n(\mathbb{Z})$

**Theorem (Kaluba, M., Nowak, 2022)**

$\Delta_1 - 0.32l \geq 0$  for  $SL_3(\mathbb{Z})$ .

# Spectral gaps for $SL_n(\mathbb{Z})$

## Theorem (Kaluba, M., Nowak, 2022)

$\Delta_1 - 0.32l \geq 0$  for  $SL_3(\mathbb{Z})$ .

- not sufficient for induction! – we need Adj:

# Spectral gaps for $SL_n(\mathbb{Z})$

## Theorem (Kaluba, M., Nowak, 2022)

$\Delta_1 - 0.32l \geq 0$  for  $SL_3(\mathbb{Z})$ .

- not sufficient for induction! – we need Adj:

# Spectral gaps for $SL_n(\mathbb{Z})$

## Theorem (Kaluba, M., Nowak, 2022)

$\Delta_1 - 0.32l \geq 0$  for  $SL_3(\mathbb{Z})$ .

- not sufficient for induction! – we need Adj:

## Theorem (Kaluba, M., 2023)

$\text{Adj} - 0.217l \geq 0$  for  $SL_3(\mathbb{Z})$ .

# Spectral gaps for $SL_n(\mathbb{Z})$

## Theorem (Kaluba, M., Nowak, 2022)

$\Delta_1 - 0.32l \geq 0$  for  $SL_3(\mathbb{Z})$ .

- not sufficient for induction! – we need Adj:

## Theorem (Kaluba, M., 2023)

$\text{Adj} - 0.217l \geq 0$  for  $SL_3(\mathbb{Z})$ .



# Spectral gaps for $SL_n(\mathbb{Z})$

## Theorem (Kaluba, M., Nowak, 2022)

$\Delta_1 - 0.32l \geq 0$  for  $SL_3(\mathbb{Z})$ .

- not sufficient for induction! – we need Adj:

## Theorem (Kaluba, M., 2023)

$\text{Adj} - 0.217l \geq 0$  for  $SL_3(\mathbb{Z})$ .

## Corollary (Kaluba, M., 2023)

For  $SL_n(\mathbb{Z})$ , one has  $\Delta_1 - 0.217(n - 2)l \geq 0$ .

# Final remarks

# Spectral gaps for $\Delta$ and $\Delta_1$

# Spectral gaps for $\Delta$ and $\Delta_1$

- recall:

Ozawa:  $(T) \Leftrightarrow \Delta^2 - \lambda\Delta \geq 0$ ,

Bader, Nowak, Sauer:  $(T) \Leftrightarrow \Delta_1 - \lambda I \geq 0$

# Spectral gaps for $\Delta$ and $\Delta_1$

- recall:

Ozawa:  $(T) \Leftrightarrow \Delta^2 - \lambda\Delta \geq 0$ ,

Bader, Nowak, Sauer:  $(T) \Leftrightarrow \Delta_1 - \lambda I \geq 0$

- $d_0 = \begin{bmatrix} 1 - s_i \\ \vdots \\ 1 - s_n \end{bmatrix}$ ,  $\Delta = d_0^* d_0$ ,  $\Delta_1 = d_0 d_0^* + d_1^* d_1$

# Spectral gaps for $\Delta$ and $\Delta_1$

- recall:

Ozawa:  $(T) \Leftrightarrow \Delta^2 - \lambda\Delta \geq 0$ ,

Bader, Nowak, Sauer:  $(T) \Leftrightarrow \Delta_1 - \lambda I \geq 0$

- $d_0 = \begin{bmatrix} 1 - s_i \\ \vdots \\ 1 - s_n \end{bmatrix}$ ,  $\Delta = d_0^* d_0$ ,  $\Delta_1 = d_0 d_0^* + d_1^* d_1$

- $d_1 d_0 = 0$

# Spectral gaps for $\Delta$ and $\Delta_1$

- recall:

Ozawa:  $(T) \Leftrightarrow \Delta^2 - \lambda\Delta \geq 0$ ,

Bader, Nowak, Sauer:  $(T) \Leftrightarrow \Delta_1 - \lambda I \geq 0$

- $d_0 = \begin{bmatrix} 1 - s_i \\ \vdots \\ 1 - s_n \end{bmatrix}$ ,  $\Delta = d_0^* d_0$ ,  $\Delta_1 = d_0 d_0^* + d_1^* d_1$

- $d_1 d_0 = 0$

- $\Delta_1 - \lambda I \geq 0 \Rightarrow \Delta^2 - \lambda\Delta = d_0^* (\Delta_1 - \lambda I) d_0 \geq 0$

# Diminishing the support – what we have



## Diminishing the support – what we have

- for  $SL_3(\mathbb{Z})$ ,  $\Delta_1 - 0.32I \geq 0$ , i.e. there exist such that  $\Delta_1 - 0.32I = M_1^* M_1 + \dots + M_k^* M_k$

## Diminishing the support – what we have

- for  $SL_3(\mathbb{Z})$ ,  $\Delta_1 - 0.32I \geq 0$ , i.e. there exist such that  $\Delta_1 - 0.32I = M_1^* M_1 + \dots + M_k^* M_k$
- $M_i$  can be supported on ball of radius 1 with respect to Jacobian support! – consisting of 19 elements only

## Diminishing the support – what we have

- for  $SL_3(\mathbb{Z})$ ,  $\Delta_1 - 0.32I \geq 0$ , i.e. there exist such that  $\Delta_1 - 0.32I = M_1^* M_1 + \dots + M_k^* M_k$
- $M_i$  can be supported on ball of radius 1 with respect to Jacobian support! – consisting of 19 elements only
- if we try to do the same for Adj part, we end up with negative  $\lambda \dots$

## Diminishing the support – what we have

- for  $SL_3(\mathbb{Z})$ ,  $\Delta_1 - 0.32I \geq 0$ , i.e. there exist such that  $\Delta_1 - 0.32I = M_1^* M_1 + \dots + M_k^* M_k$
- $M_i$  can be supported on ball of radius 1 with respect to Jacobian support! – consisting of 19 elements only
- if we try to do the same for Adj part, we end up with negative  $\lambda \dots$
- ... on other hand, for  $SL_4(\mathbb{Z})$ , we have  $\text{Adj} - 0.009I = N_1^* N_1 + \dots + N_l^* N_l$  for  $N_i$  supported on ball of radius 1

# Diminishing the support – Zuk's like condition?

## Diminishing the support – Zuk's like condition?

- $G = \langle S | \dots \rangle$ ,  $S$  – symmetric, i.e.  $S$  is the ball of radius 1 with respect to itself

## Diminishing the support – Zuk's like condition?

- $G = \langle S | \dots \rangle$ ,  $S$  – symmetric, i.e.  $S$  is the ball of radius 1 with respect to itself
- $\Gamma = (V, E)$ ,  $V = S$ ,  $E = \{(s, t) | s^{-1}t \in S\}$

## Diminishing the support – Zuk's like condition?

- $G = \langle S | \dots \rangle$ ,  $S$  – symmetric, i.e.  $S$  is the ball of radius 1 with respect to itself
- $\Gamma = (V, E)$ ,  $V = S$ ,  $E = \{(s, t) | s^{-1}t \in S\}$
- $\Delta_\Gamma : \ell^2(V) \rightarrow \ell^2(V)$ ,  $\Delta_\Gamma f(s) = f(s) - \frac{1}{\deg(s)} \sum_{(s,s') \in E} f(s')$



## Diminishing the support – Zuk's like condition?

- $G = \langle S | \dots \rangle$ ,  $S$  – symmetric, i.e.  $S$  is the ball of radius 1 with respect to itself
- $\Gamma = (V, E)$ ,  $V = S$ ,  $E = \{(s, t) | s^{-1}t \in S\}$
- $\Delta_\Gamma : \ell^2(V) \rightarrow \ell^2(V)$ ,  $\Delta_\Gamma f(s) = f(s) - \frac{1}{\deg(s)} \sum_{(s,s') \in E} f(s')$

## Diminishing the support – Zuk's like condition?

- $G = \langle S | \dots \rangle$ ,  $S$  – symmetric, i.e.  $S$  is the ball of radius 1 with respect to itself
- $\Gamma = (V, E)$ ,  $V = S$ ,  $E = \{(s, t) | s^{-1}t \in S\}$
- $\Delta_\Gamma : \ell^2(V) \rightarrow \ell^2(V)$ ,  $\Delta_\Gamma f(s) = f(s) - \frac{1}{\deg(s)} \sum_{(s,s') \in E} f(s')$

### Theorem (Zuk, 2003)

*If  $\lambda_1 > \frac{1}{2}$ , where  $\lambda_1$  is the smallest non-zero eigenvalue of  $\Delta_\Gamma$ , then  $G$  has property (T).*

## Diminishing the support – Zuk's like condition?

- $G = \langle S | \dots \rangle$ ,  $S$  – symmetric, i.e.  $S$  is the ball of radius 1 with respect to itself
- $\Gamma = (V, E)$ ,  $V = S$ ,  $E = \{(s, t) | s^{-1}t \in S\}$
- $\Delta_\Gamma : \ell^2(V) \rightarrow \ell^2(V)$ ,  $\Delta_\Gamma f(s) = f(s) - \frac{1}{\deg(s)} \sum_{(s,s') \in E} f(s')$

### Theorem (Zuk, 2003)

*If  $\lambda_1 > \frac{1}{2}$ , where  $\lambda_1$  is the smallest non-zero eigenvalue of  $\Delta_\Gamma$ , then  $G$  has property (T).*

- follow up problem: can we do something similar for  $\Delta_1$ ?

Thank you for your  
attention!