# Spectral gaps for higher Laplacians and group cohomology 

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Introduction
Motivation

Vanishing, reducibility, (T)

## Motivation


point reflection

rotation


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rotation


- Generalization: symmetries must have fixed points


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- An "isometric" fixed point property: Kazhdan's Property (T)


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- Generalization: symmetries must have fixed points
- An "isometric" fixed point property: Kazhdan's Property (T)
- (T) can be applied to construct expanders


## Aims and methods

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- Goal: study cohomological conditions generalizing property ( T )


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- The conditions: vanishing and reducibility of group cohomology
- A criterion for vanishing and reducibility is provided by Laplacians
- Idea: interpretation in a group ring setting

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- one defines group cohomology for an arbitrary group module
- there are several ways to compute group cohomology
- one may use e.g. projective resolutions:

$$
\begin{gathered}
\mathcal{F}=\cdots F_{n} \rightarrow \cdots \rightarrow F_{0} \rightarrow \mathbb{Z} \rightarrow 0 \\
H^{n}(G, V)=H_{n}\left(\operatorname{Hom}_{G}(\mathcal{F}, V)\right)
\end{gathered}
$$

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Theorem (Ozawa, 2014)
$G=\left\langle s_{1}, \ldots, s_{n} \mid \cdots\right\rangle$ has property $(T)$ iff there exists $\lambda>0$ such that $\Delta_{0}^{2}-\lambda \Delta_{0}=\sum \xi_{i}^{*} \xi_{i}\left(\Delta_{0}=d_{0}^{*} d_{0}=\sum_{i=1}^{n}\left(1-s_{i}\right)^{*}\left(1-s_{i}\right)\right)$.

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## Definition

The ith reduced cohomology is defined by $\bar{H}^{i}=\operatorname{Ker} d_{i} / \overline{\operatorname{lm} d_{i-1}}$. We say that the $i$ th cohomology is reduced if $H^{i}$ coincides with $\bar{H}^{i}$.

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## Proposition (Dymara-Januszkiewicz)

For any $i \geq 2$ there exists a group $G_{i}$ with reduced $H^{i}$ and $H^{i}\left(G, \rho_{0}\right) \neq 0$ for some unitary representation $\rho_{0}$.

## Spectral gaps for higher Laplacians vs vanishing and reducibility

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## Definition

$M \in M_{n}(\mathbb{R} G)$ is an SOS if there exist $M_{1}, \ldots, M_{l}$ such that

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M=M_{1}^{*} M_{1}+\cdots+M_{l}^{*} M_{l} .
$$

## Algebraic condition

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- $\Delta_{i}-\lambda I=$ SOS for some $\lambda>0$.


## Fox calculus

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The differentials $\frac{\partial}{\partial s_{j}}: \mathbb{R} F_{n} \rightarrow \mathbb{R} G, F_{n}=\left\langle s_{1}, \ldots, s_{n}\right\rangle$ are defined by:

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The Fox derivatives are the elements $\frac{\partial r_{i}}{\partial s_{j}} \in \mathbb{R} G$.

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## Theorem (Lyndon, '50s)

The cohomology $H^{*}(G, V)$ is the cohomology of the following complex:

$$
0 \rightarrow V \xrightarrow{d_{0}} V^{n} \xrightarrow{d_{1}} V^{m} \rightarrow \cdots .
$$

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$\left.00 \rightarrow V \xrightarrow{\left[\begin{array}{l}1-a \\ 1-b\end{array}\right]} V^{2} \xrightarrow{\left[1+a-a^{2} b a^{-1}\right.} \quad a^{2}+a^{2} b a^{-1}\right]=d_{1} ~ V$


# Spectral gap for the first Laplacian of $\mathrm{SL}_{3}(\mathbb{Z})$ 

(joint work with M. Kaluba and P. Nowak)

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## Lemma

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- Convex optimization for $M=\Delta_{1}-\lambda /$ :

$$
\begin{aligned}
\text { maximize: } & \lambda \\
\text { subject to: } & M_{i, j}(g)=\left\langle\delta_{i, j} \otimes \delta_{g}, P\right\rangle, \\
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\mathrm{SL}_{3}(\mathbb{Z})= & \left\langle\left\{E_{i, j}\right\}\right|\left[E_{i, j}, E_{i, k}\right],\left[E_{i, j}, E_{j, k}\right] E_{i, k}^{-1}, \\
& \left.\left(E_{1,2} E_{2,1}^{-1} E_{1,2}\right)^{4}\right\rangle
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Theorem (Kaluba, M., Nowak)
For $\mathrm{SL}_{3}(\mathbb{Z})$ the expression $\Delta_{1}-\lambda /$ is an SOS for any $\lambda \leq 0.32$.

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For $\mathrm{SL}_{3}(\mathbb{Z})$ the expression $\Delta_{1}-\lambda /$ is an SOS for any $\lambda \leq 0.32$.

## Corollary

The first cohomology of $\mathrm{SL}_{3}(\mathbb{Z})$ vanishes, and the second is reduced.

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- (T) yields expanders: $G_{n}:=G / N_{n}, G$ has $(T)$
- Expanders generalize to higher dimensions (Lubotzky)
- $\mathrm{SL}_{3}(\mathbb{Z})$ : spectral gap $\Rightarrow$ " CW -expanders"


## Thank you for attention!

